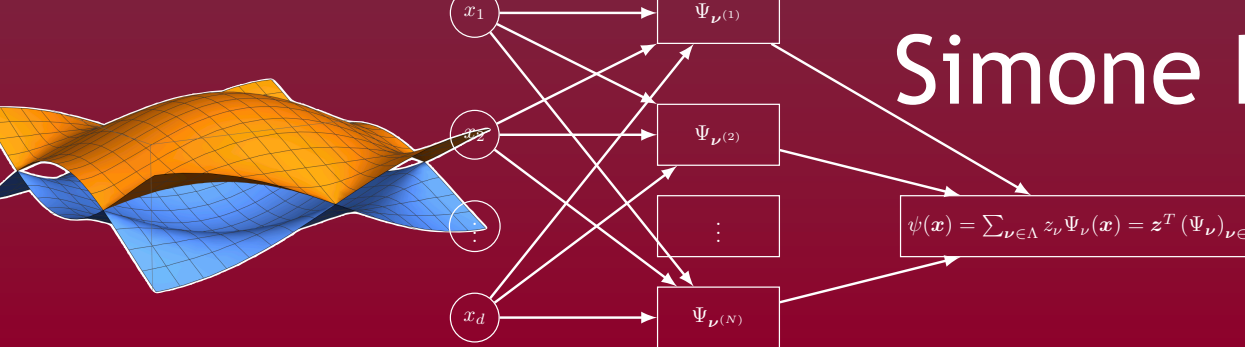


# Physics-informed deep learning for high-dimensional diffusion-reaction equations



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## 1. Deep learning for high-dimensional PDEs

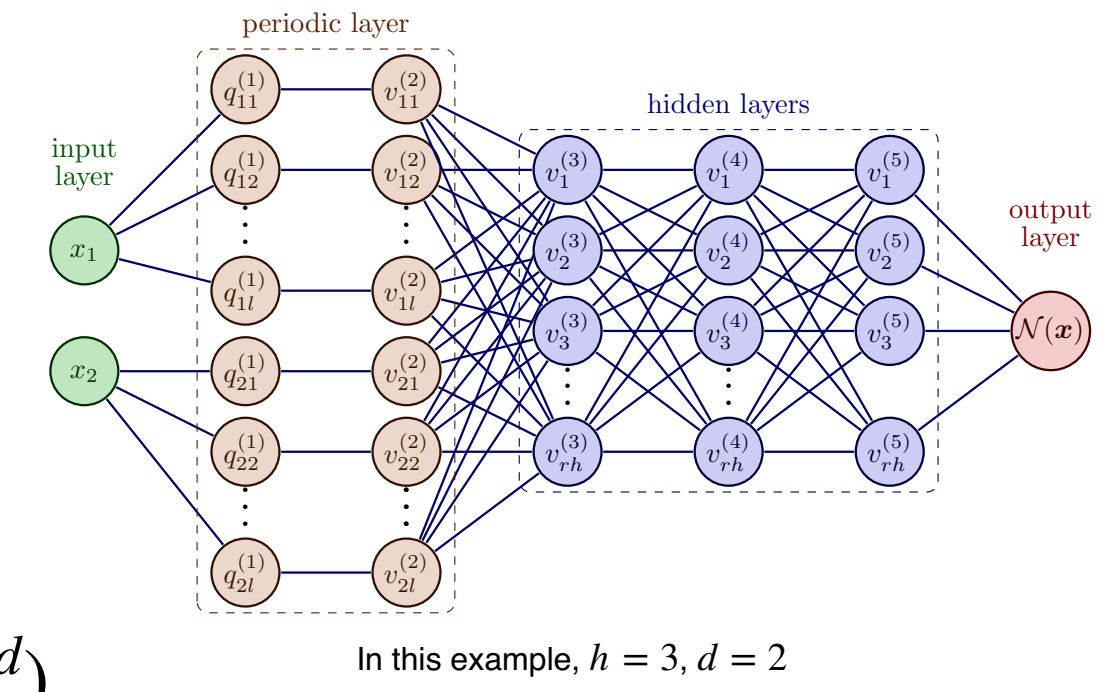
In scientific machine learning, Physics-Informed Neural Networks (PINNs) have emerged as a powerful tool to solve high-dimensional Partial Differential Equations (PDEs), from computational finance (Black-Scholes) to statistical mechanics (many-electron Schrödinger equation).

- \* **Key challenge:** classical methods are not easily applied to high-dimensional settings requiring huge amounts of data to converge.  $\implies$  exponential scaling of data.
- $\hookrightarrow$  high computational cost.
- $\hookrightarrow$  inefficient in modern applications.
- \* **Recent results** have shown that deep neural networks (DNNs) are exceptionally good at tackling rising dimensions<sup>7,5</sup>.

\* **Goal:** approximate  $u \in H^2(\mathbb{T}^d)$  s.t.  
 $\mathcal{L}[u](x) := -\nabla \cdot (a(x) \nabla u(x)) + \rho u(x) = f(x), \quad \forall x \in \mathbb{T}^d$ , given  
 $a \in C^1(\mathbb{T}^d), \quad \min_{x \in \mathbb{T}^d} a(x) \geq a_{\min} > 0, \quad \rho > 0, \quad \text{and} \quad f \in L^2(\mathbb{T}^d)$ .

## 2. Setup

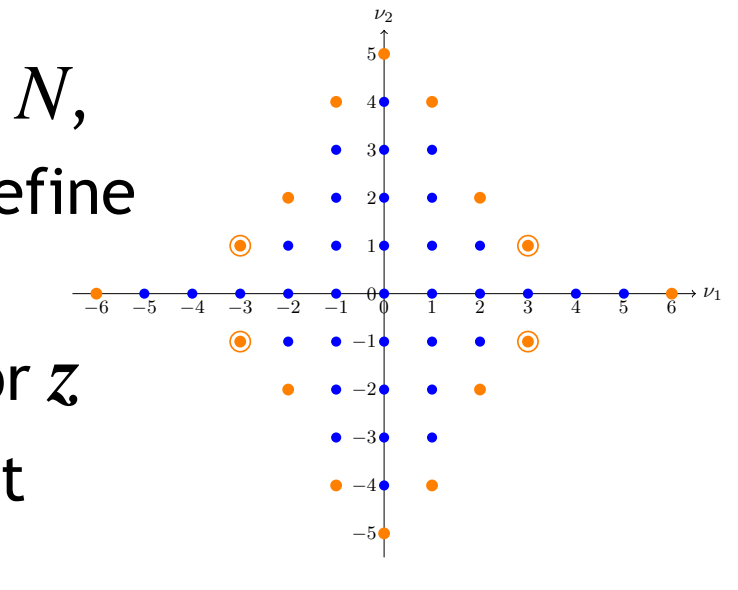
- \* **Model architecture:** with component-wise activations  
 $\sigma^{(k)}(\mathbf{x}) = (\sigma_j^{(k)}(x_j)),$   
 $\sigma_j(x_j) = x_j$  linear or RePU $^\ell$  i.e.  
 $\text{RePU}_\ell(x) := \max\{0, x^\ell\}, \ell \in \mathbb{N}.$
- \* **Periodic layer:** enforce periodic boundary conditions.
- \* **Sample points:**  $\mathbf{x}_1, \dots, \mathbf{x}_m \sim \text{Unif}(\mathbb{T}^d)$ ,
- \* **Train:** by minimizing regularized Root Mean Square Error (RMSE) (★).



\* **In theory:**  
 • **Normalize** Fourier orthonormal basis of  $L^2$ ,  $\Psi_\nu = \frac{\exp(2\pi i \nu \cdot \mathbf{x})}{4\pi^2 \|\nu\|_2^2 + \rho/a_0}$   
 $\hookrightarrow$  Train only last layer  
 $\hookrightarrow$  **Replicate** basis in rest of network.

## 3. Compressive Fourier Collocation (CFC)<sup>8</sup>

Given a rescaled Fourier basis  $\{\Psi_\nu\}_{\nu \in \Lambda}$ ,  $|\Lambda| = N$ ,  $m$  i.i.d. points  $\mathbf{x}_1, \dots, \mathbf{x}_m \in \mathbb{T}^d$ , and  $m \ll N$ , define  
 $Az = b,$   
 where  $A_{ij} = \mathcal{L}[\Psi_{\nu_j}](\mathbf{x}_i)$  and  $b_i = f(\mathbf{x}_i)$ . Solve for  $z$  using *lower Orthogonal Matching Pursuit*<sup>7</sup> and set  
 $\hat{u} = \sum_{\nu \in \Lambda} \hat{c}_\nu \Psi_\nu.$



## 4. Main result (Practical Existence Theorem (PET))

**Theorem.** Given  $d, s, n, \ell \in \mathbb{N}$ , with  $\ell \geq 2$ , and  $\epsilon \in (0,1)$ , there exist:  
 1. a class of neural networks  $\mathcal{N}$ , of the form described above, s.t.  
 $\forall \psi \in \mathcal{N}$ , width( $\psi$ ), depth( $\psi$ ) are at most polynomial in  $d$ .  
 2. a regularization function  $\mathcal{R} : \mathcal{N} \rightarrow [0, \infty)$ ,  
 3. a choice of tuning parameter  $\lambda$  depending only on  $a, \rho$ , and  $s$ ,  
 s.t. the following holds with probability at least  $1 - \epsilon$ . Under *suitable sufficient conditions* on the PDE parameters, let  
 $m \gtrsim_{a,\rho} s \log^2(2s) \cdot (\min\{\log(n) + d, \log(2n)\log(2d)\} + \log(\epsilon^{-1})).$   
 Then, every minimizer  $\hat{\psi}$  of

$$(\star) \quad \min_{\psi \in \mathcal{N}} \sqrt{\frac{1}{m} \sum_{i=1}^m |\mathcal{L}[\psi](\mathbf{x}_i) - f(\mathbf{x}_i)|^2} + \lambda \mathcal{R}(\psi), \quad \text{satisfies}$$

$$\|u - \hat{\psi}\|_{L^2} + \|(\Delta - \rho)(u - \hat{\psi})\|_{L^2} \lesssim_{a,\rho,d} \frac{\sigma_s(\mathbf{c}_\Lambda)_1}{\sqrt{s}} \cdot \left( \frac{\|u - u_\Lambda\|_{W^{2,\infty}}}{\sqrt{s}} + \|u - u_\Lambda\|_{H^2} \right).$$

and, if  $\rho < 1$ ,

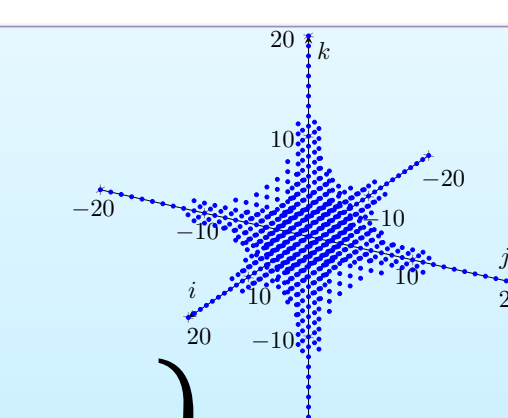
$$\|u - \hat{\psi}\|_{H^2} \lesssim_{a,\rho,d} \frac{\sigma_s(\mathbf{c}_\Lambda)_1}{\sqrt{s}} \cdot \left( \frac{\|u - u_\Lambda\|_{W^{2,\infty}}}{\sqrt{s}} + \|u - u_\Lambda\|_{H^2} \right).$$

(at most linear dependence on  $d$  in the hidden constants)

## 5. Proof sketch

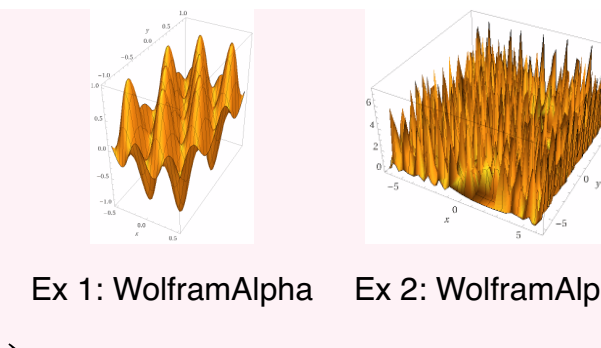
1. Replicate  $\{\Psi_\nu\}_{\nu \in \Lambda}$ , while tracking width and depth of each layer. The index set is the *hyperbolic cross*<sup>4</sup>  

$$(*) \quad \Lambda = \Lambda_{d,n}^{\text{HC}} := \left\{ \nu \in \mathbb{Z}^d : \prod_{k=1}^d (|\nu_k| + 1) \leq n \right\}$$
2. Show  $\{\mathcal{L}[\Psi_\nu]\}_{\nu \in \Lambda}$  is *Bounded Riesz System (BRS)*<sup>2</sup> under sufficient conditions on  $a, \rho$ , and  $f$ .
3. BRS + lower bound on sample complexity  $m \implies$  SR-LASSO recovery guarantees  $\implies$  stable, accurate PDE solution.



## 6. Numerics

\* Compare the performance of PINNs with CFC.  
 Fix a sparse diffusion function  
 $a(\mathbf{x}) = 1 + 0.25 \sin(2\pi x_1) \sin(2\pi x_2),$   
 and consider solutions  
 $u_1(x) = \sin(4\pi x_1) \sin(2\pi x_2),$  (Example 1)  
 $u_2(x) = \exp(\sin(2\pi x_1) + \sin(2\pi x_2)),$  (Example 2)  
 $u_3(x) = \exp\left(\sum_{k=1}^d \frac{1}{k^2} \sin(2\pi x_k)\right),$  (Example 3)



## 7. Key takeaways

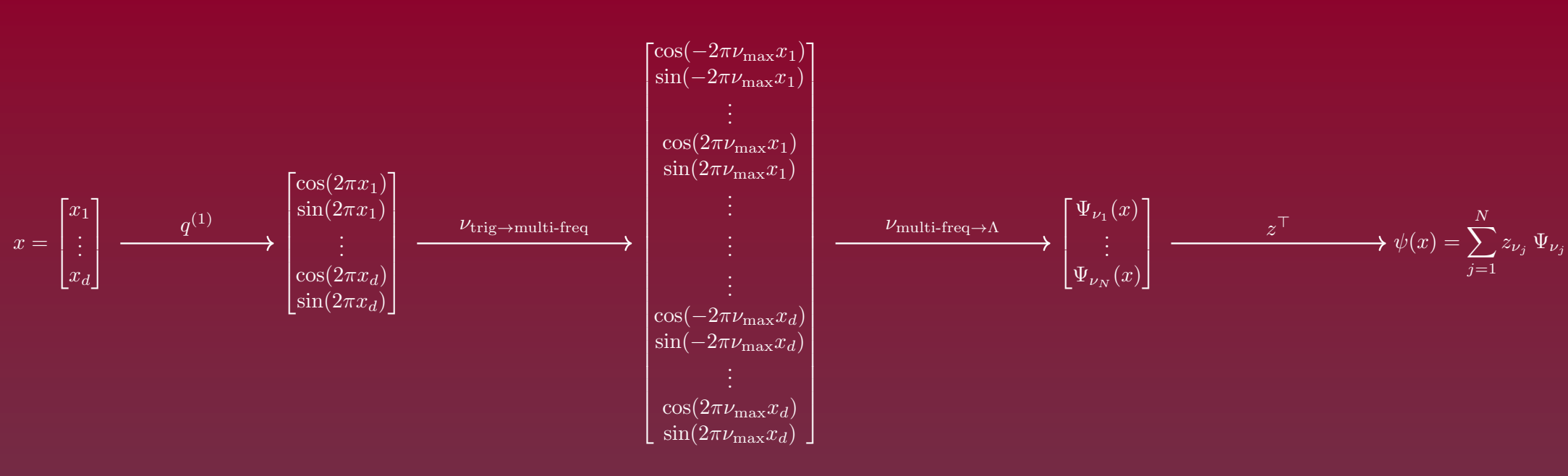
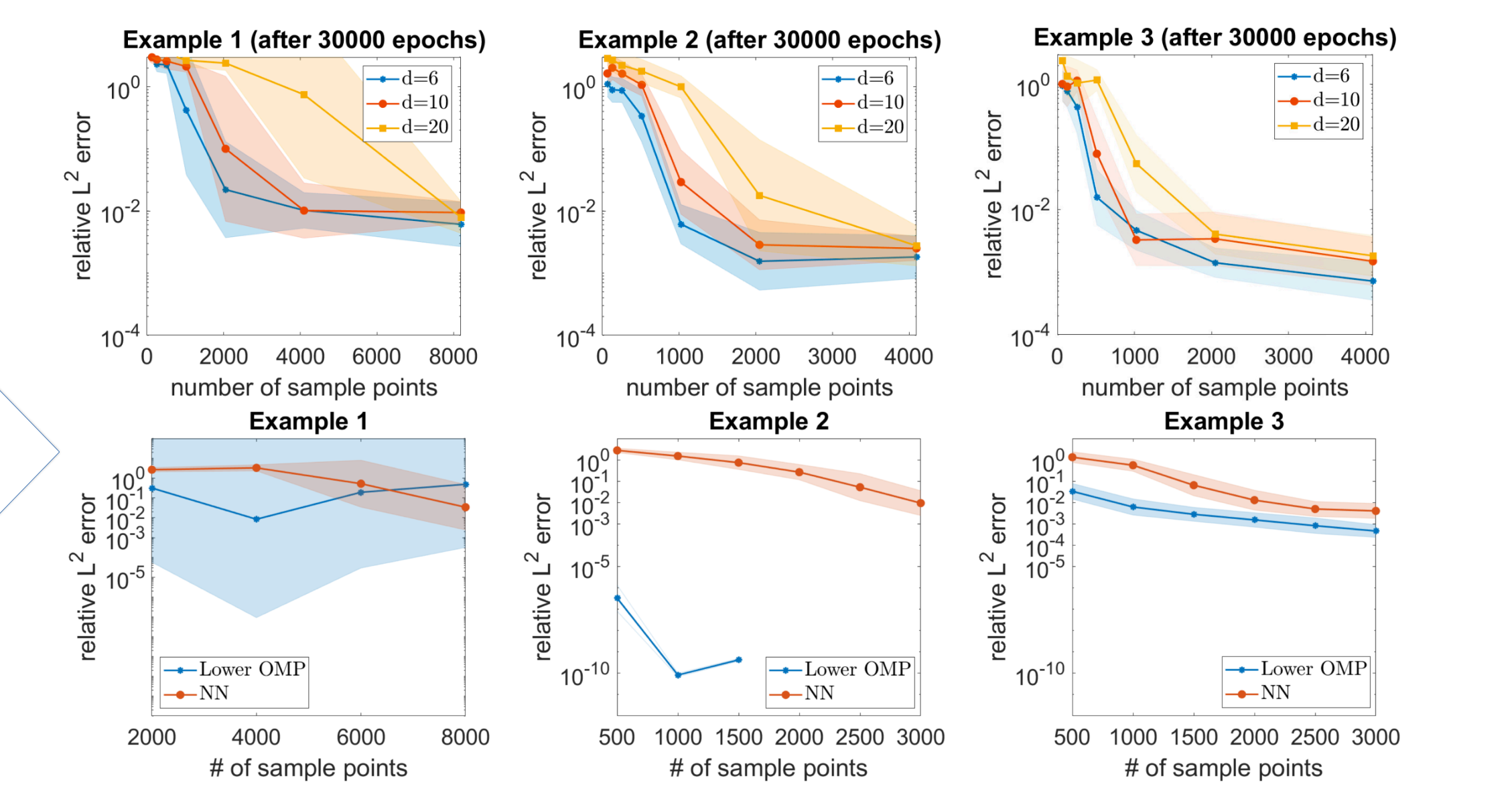
- \* A novel convergence result (PET) for PINNs with logarithmic, or at worst, linear scaling of the sample complexity  $m$  with dimension.
- \* DNNs can compete with a state-of-the-art PDE solver (CFC).
- \* An improvement on *uniform approximation theorems*.  
 $\hookrightarrow$  These imply the existence of networks with favourable approximation properties (no sample complexity, training optimization, ...)

## 8. Limitations

Gap between theory and practice:  
 $\hookrightarrow$  in practice, variations of Stochastic Gradient Descent (SGD) are used to train the *whole* network; in theory, partial training only.  
 $\hookrightarrow$  in practice, loss is roughly minimized by SGD, but min is exact in theory.  
 $\implies$  To replicate  $\{\Psi_\nu\}_{\nu \in \Lambda}$ , we use RePU and linear activations, which can exactly emulate *products*<sup>5</sup>, but are not as standard as ReLU or tanh.

$$F_\nu(\mathbf{x}) = \exp(2\pi i \nu \cdot \mathbf{x}) = \prod_{j \in \text{supp}(\nu)} \exp(2\pi i \nu_j x_j)$$

- \* Some open problems and improvements:
  - How to quantify the error induced by approximate min problems?
  - How to deal with switching to standard activations? (CFC, products, ...)
  - How to find *necessary* sufficient conditions on the PDE parameters?



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Physics-Informed Deep Learning and Compressive Collocation for High-Dimensional Diffusion-Reaction Equations: Practical Existence Theory and Numerics

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Abstract  
 On the border of scientific computing, Deep Learning (DL), a machine learning with Deep Neural Networks (DNN), has emerged as a powerful tool to solve high-dimensional Partial Differential Equations (PDEs). In this paper, we propose a novel approach to solve high-dimensional PDEs by combining the power of DL with the power of Compressive Fourier Collocation (CFC). We show that the proposed method can achieve high accuracy with a significantly smaller number of sample points compared to standard methods. In particular, we demonstrate that the proposed method can achieve high accuracy with a significantly smaller number of sample points compared to standard methods.